Tracking Single Particles using Surface Plasmon Leakage Radiation Speckle

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MOTIVATION

- Detection and tracking of single nanometre scale biological molecules: small particles interact only weakly with light
- Enhance light-matter interaction using plasmonics: confined surface modes give strong local fields
- Interference with strong background field to increase sensitivity: Interferometric signals are sensitive to small phase perturbations²

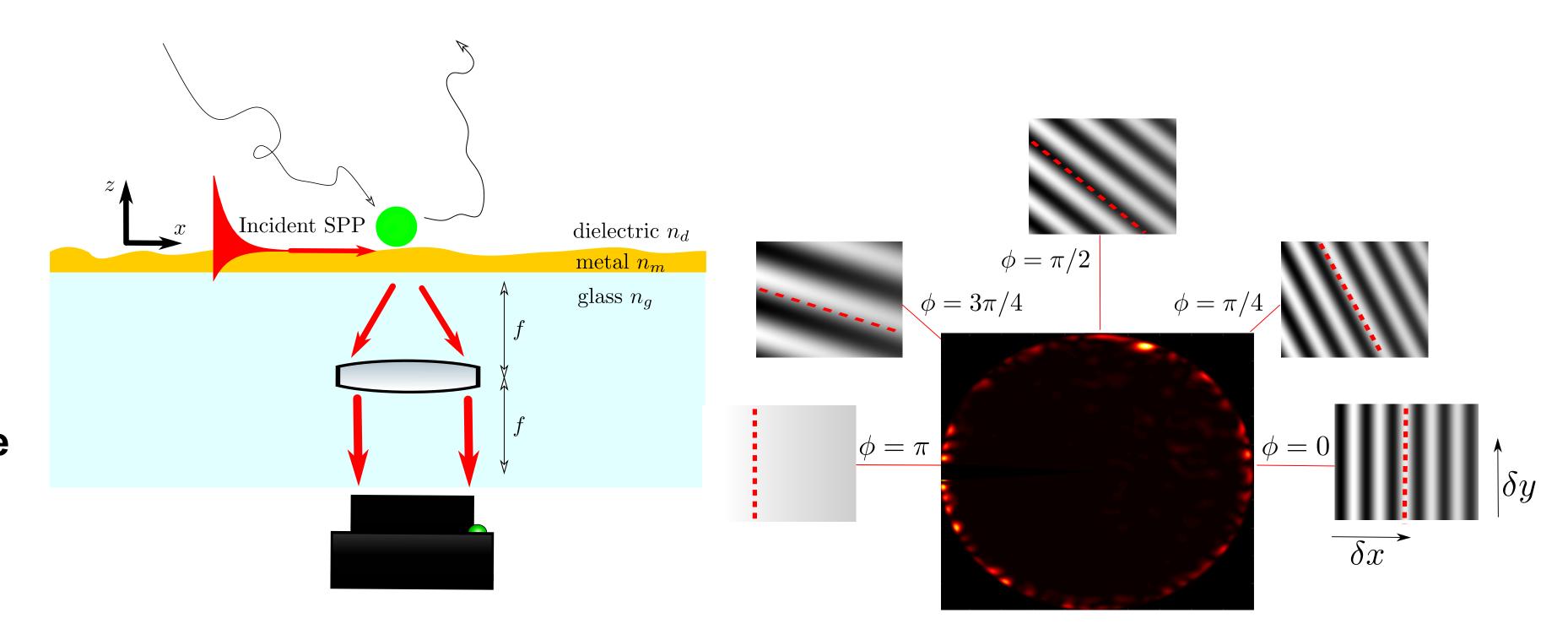
Principle

- ➤ Scattered light strongly confined to cone: due to conservation of SPP momentum³
- ► Random scattering by rough surface: random interference of wavefronts gives speckle pattern
- Light scattered by analyte particle has known phase (and amplitude) dependence on particle position: fringe patterns at different directions, ϕ , on the cone as the analyte particle moves (assuming single scattering)
- Random speckle phase: unknown random offsets of fringe pattern, different for each ϕ
- ► Eliminate unknown phase using 3 frames in particle trajectory
- ➤ Solve simultaneously the N equations for N pixels around the ring for analyte particle displacement between frames

$$(\hat{\boldsymbol{r}}_{12},\hat{\boldsymbol{r}}_{23}) = \operatorname*{arg\,min}_{(\boldsymbol{r_{12},r_{23}})} \sum_{j=1}^{N} \left(rac{oldsymbol{u}(\phi_j) \cdot oldsymbol{\Delta}(\phi_j)}{|oldsymbol{u}(\phi_j)|}
ight)^2$$

Results

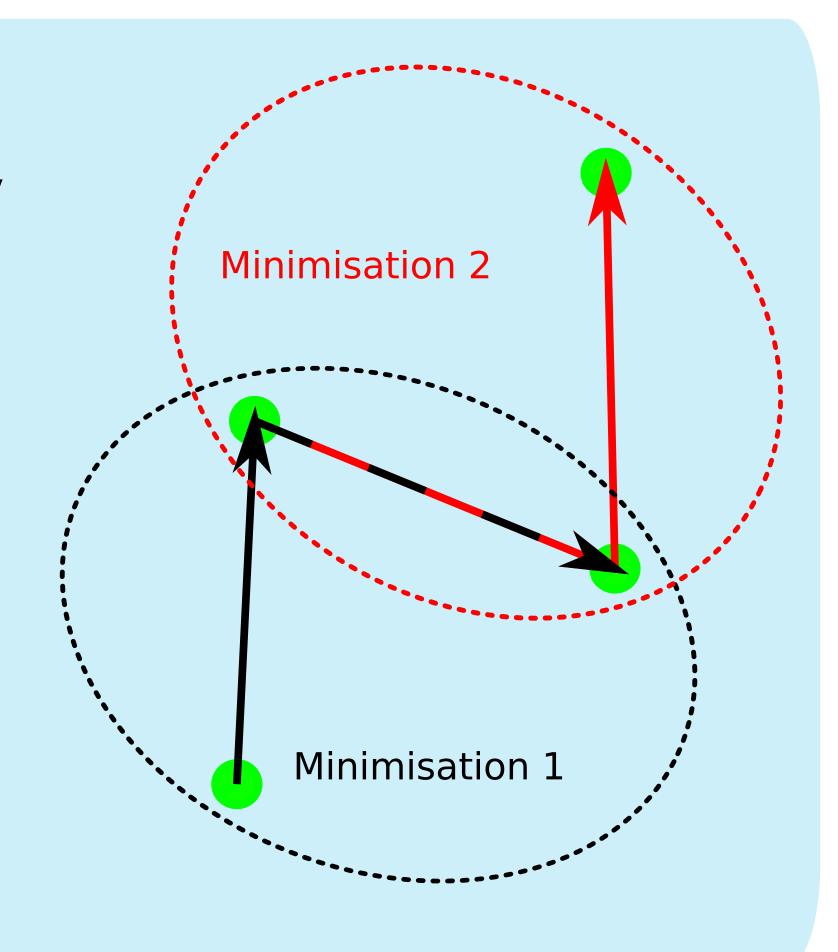
- ► Results from simulations: point scatterer undergoing random walk with 90nm step size
- ► Error in step estimate depends on the fringe amplitude relative to:
 - A) the background speckle intensity (signal to background ratio, SBR)
 - B) the shot noise level (differential signal to noise ratio, dSNR)
- Two regimes where algorithm performs poorly:
 - A) SBR≥1, directly scattered intensity no longer negligible relative to interference
 - B) low dSNR, noise levels comparable to fringe amplitude
- ➤ Optimal working regime: achieves errors of order 1%, corresponding to subnanometre precision

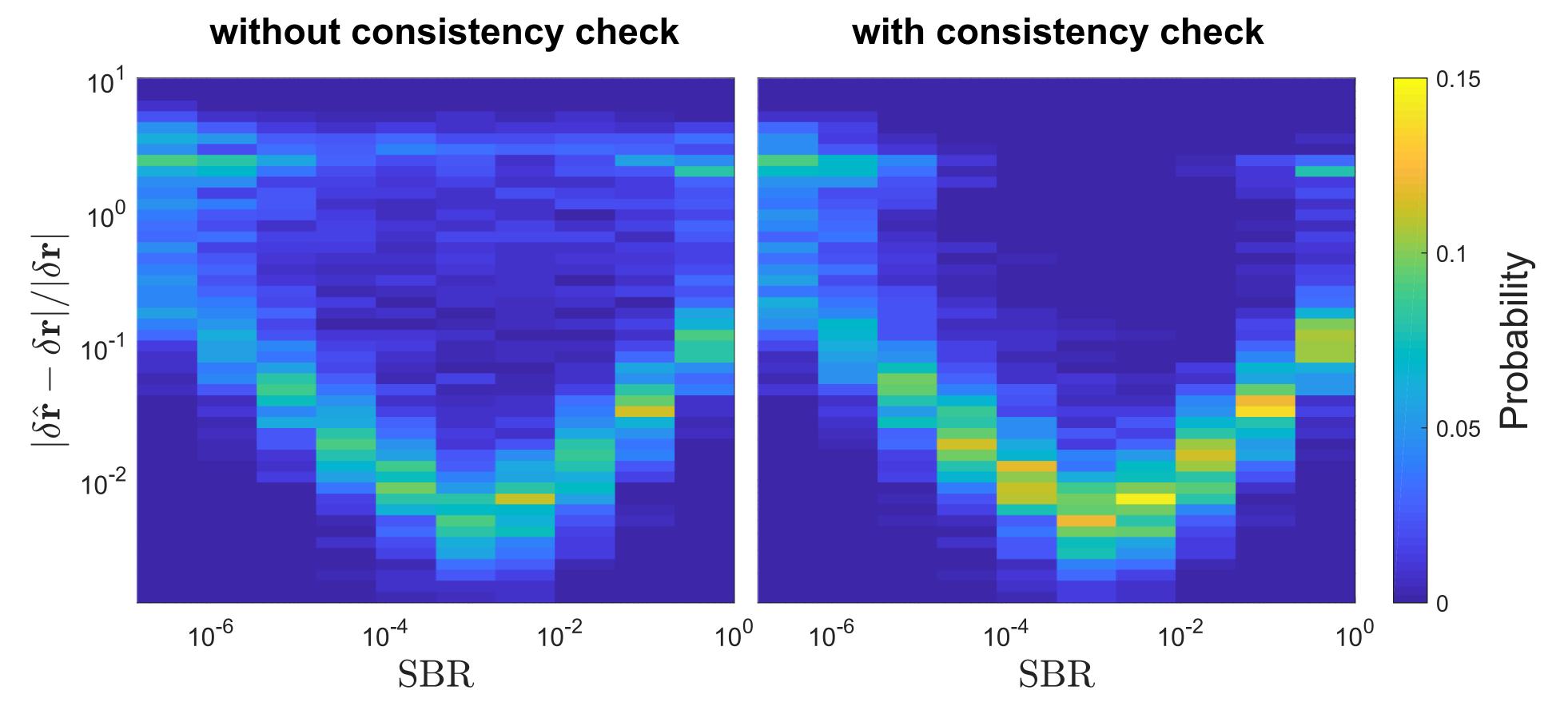


	Performance	Shot Noise limit	'Dark' Noise
	Metric		limit
Dark Field	SNR = dSNR	$\sqrt{N_s}$	$N_s/\sqrt{N_d}\ll 1$
	SBR	$N_s/N_d\gg 1$	$N_s/N_d \ll 1$
Interference	SNR	$\sqrt{N_b} \gg 1$	$\sqrt{N_b} \gg 1$
	SBR	$\sqrt{N_s/N_b} \ll 1$	$\sqrt{N_s/N_b} \ll 1$
	dSNR	$\sqrt{N_s}$	$\sqrt{N_s}$

Consistency Check

- ➤ Global least squares minimisation: may converge to local minimum
- ► Require consistency of step estimates: run minimisation procedure with new start points until consistent trajectory achieved
- ➤ Potential sign ambiguity: symmetry of system means exact opposite transverse steps give same phase shift
- ► Flip transverse steps estimates if it improves consistency





- 1. J. Homola, S. S. Yee, and G. Gauglitz, "Surface plasmon resonance sensors: review," Sensors Actuators B54, 3-15 (1999).
- 2. R. W. Taylor and V. Sandoghdar, "Interferometric Scattering Microscopy: Seeing Single Nanoparticles and Molecules via Rayleigh Scattering" Nano Lett. 19, 4827-4835 (2019).
- 3. S. A. Maier, "Plasmonics: Fundamentals and Applications" (Springer, 2007), 1st ed.