

# Optimal frames for polarisation state reconstruction

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for the science of light



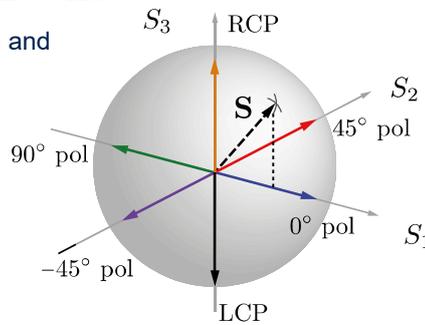
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## INTRODUCTION

- **Measurement of polarisation of light:** is a common problem in e.g. quantum information, astronomy, quantitative biology and single molecule orientational imaging.
- **Classical polarimetry:** Complete polarisation state reconstruction requires at least 4 projective measurements of the Stokes vector. Larger measurement frames can improve noise performance. We have derived optimal frames with an arbitrary number,  $m$ , of analysis states.
- **Nonlinear measurements and quantum state tomography:** polarisation dependent optical nonlinear processes can give insights into crystal and molecular structure, whilst higher order polarisation properties can contain "hidden" polarisation correlations, which are of interest both in a quantum and in a classical context. We present optimal measurement frames for reconstruction of such higher order properties.

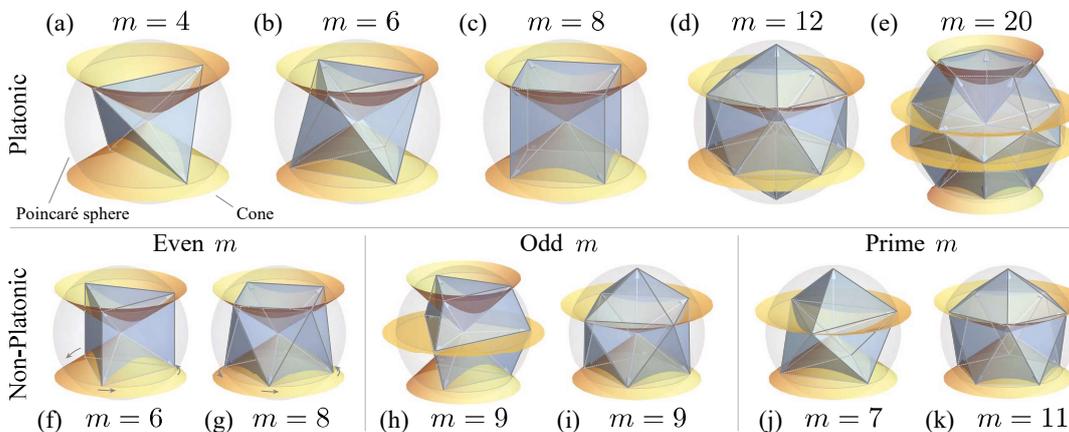
## Linear reconstruction and spherical designs

- ▶ **Linear measurement:** described by projection matrix  $\mathbf{D} = \mathbb{A}\mathbf{S}$
- ▶ **Condition number:** characterises stability of inversion and bounds noise amplification  $\kappa = \|\mathbb{A}\| \|\mathbb{A}^+\|$
- ▶ **Analytic minimisation:** equivalent to maximisation of determinant of Gram matrix
- ▶ **Optimal frame:** measurement states  $\mathbf{A}_j = [1, \mathbf{a}_j]/2$  must satisfy:  $\sum_{j=1}^m \mathbf{a}_j = \mathbf{0}$  and  $\sum_{j=1}^m \mathbf{a}_j \mathbf{a}_j^T = \frac{m}{N-1} \mathbb{I}_{N-1}$
- ▶ **Spherical 2 designs:** fulfil all optimality constraints



## Properties of optimal bases

- ▶ Optimal condition number is independent of  $m$ .
- ▶ Non-unique in general and non-existent for  $m = 5$ .
- ▶ For  $m = 4, 6, 8, 12$  and  $20$  can be defined by the vertices of the Platonic solids inscribed in the Poincaré sphere.
- ▶ Do not necessarily correspond to inscribed polyhedra of maximum volume
- ▶ Also optimal in sense of equally weighted variance



## Generalisation to N dimensional measurements

- ▶  $N = 3$ : linear polarimetry
- ▶  $N = 9$ : polarimetry of 3D optical fields
- ▶  $\kappa^2 = 2N^2 - 4N + 4$
- ▶  $\text{EWV} = 2\kappa^2/m$

## Higher order polarisation properties

- ▶ **Nonlinear measurands:** dependent on products of Stokes parameters upto degree  $t$
- ▶ **Sum rule:** Polynomial functions satisfy a sum rule
- ▶ **Minimum condition number:** follows from extension of the optimisation strategy. Worsens for higher order problems.
- ▶ **Spherical  $2t$  designs:** Optimal measurement frames correspond to spherical  $2t$  designs. These include the Platonic solids.

$$D(\mathbf{S}) = \sum_{k=0}^K F_k P_k(\mathbf{S})$$

$$\sum_{k=0}^K P_k^*(\mathbf{S}) P_k(\mathbf{S}) = C$$

$$\kappa^2 = \frac{C}{P_0} + \frac{CK^2}{C - P_0^2}$$

## SPHERICAL T DESIGNS

Integral of any polynomial of degree  $t$  over a sphere = the average over the set of  $m$  points

	exists iff	
2-design	$m = 4, \geq 6$	
3-design	$m = 6, 8, \geq 10$	
4-design	$m = 12, 14, \geq 20$	
5-design	$m = 12, 16, 17, 20, \geq 22$	
6-design	$m = 24, 26, \geq 28$	
7-design	$m = 24, 30, 32, 34, \geq 36$	
8-design	$m = 36, 40, 42, \geq 44$	
9-design	$m = 48, 50, 52, \geq 54$	
10-design	$m = 60, 62, \geq 64$	

- ▶ Generalisation of mutually unbiased bases

## References

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